

WARNING Disregarding this symbol may result in serious injury or death

CAUTION Disregarding this symbol may result in injury or damage to equipment

Note Special attention is required when this symbol is shown

EN16005 Setting required to conform with EN16005

1 General Description / Features

- The RAP5M-PRO is a microprocessor controlled active infrared presence detector for swing doors.
- 6 detection spots per PCB unit provide a wide detection area.
 - The detection distance to the floor is set automatically by pressing a Push Switch.
 - The detection range can be adjusted manually, using dip switches in increments of 50mm
 - The relay output can be changed from NO to NC using a dip switch.
 - Self diagnostic and monitoring functions are implemented.

2 Components

The illustration below shows the standard configuration of RAP5M-PRO with one PCB units.

Table.1 Information

Length [mm]	Filter Cover	Joint	(3)
692	2	1	3

Accessories

- (1) Installation Instruction
- (2) Wire Sheath 600 [mm]
- (3) Mounting Screws 4x 16 [mm]
- (4) Jamb Hole Cover A/B
- Mounting Screws 3x 10 [mm]

3 Mounting and Wiring Information

3.1. Notice

Note Before mounting this sensor please note the following remarks.

- Do not mount the sensor higher than 2.6 [m] (8' 6").
- Do not mount the sensor where rain or snow will fall directly on the unit.
- Ensure the minimum of reflected sunlight from the floor.
- Ensure no condensation gets onto the sensor.
- The Aluminum Case(s) should be located close to the Leading edge of the door to maximise safety detection.

6 Be careful not to drop the sensor, during transportation and installation. It will be caused of breakage failure.

3.2 Mounting Hole

WARNING Drilling may cause Electric shock! When drilling, pay attention to hidden wires.

Drill fixing holes as illustrated below. When installing on both sides of the door it may be necessary to drill a wiring hole through the door. (Ref. 3.6 Plan View of Installation)

3.3 Mounting the Aluminum Case

- Unscrew the Side Covers and remove the Filter Cover.
- Remove Angle Stabilizer.
 - Lift and slide the Angle Stabilizer to the side as indicated.
 - Push the Angle Stabilizer with your thumb to remove it from the Aluminum Case.

- Remove the PCB Unit. Loosen the Screw on the PCB Holder and slide it aside to remove the PCB Unit.
- Fix the Aluminum Case to the door with Screws.

3.4 Replacing the PCB unit(s)

CAUTION When replacing the units it is very important that the side with "LEADING EDGE" marked on it is inserted so that it is closest to the leading edge of the door. This will ensure maximum safety detection at the door edge.

- Remove the main cable Terminal block from the PCB unit.
- Attach the PCB unit, making sure that the side marked "LEADING EDGE" is closest to the leading edge of the door. Attach the Angle Stabilizer and tighten the screws on the PCB Holders.

torque 0.5 Nm

3.5 Wiring to the door controller

Install the Jamb Hole Cover and Wire Sheath when wiring to the door controller.

Drill following holes.

Clamp the Wire Sheath between the Jamb Hole Cover A/B

Wires to the controller

Jamb Hole Cover A

Wire Sheath

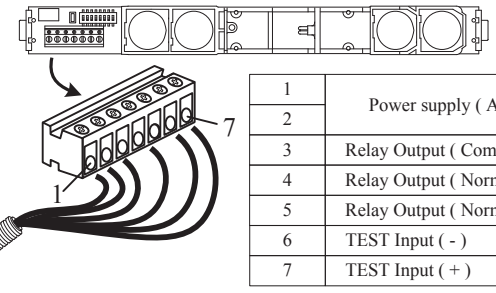
Jamb Hole Cover B

Screw (3x 10 [mm])



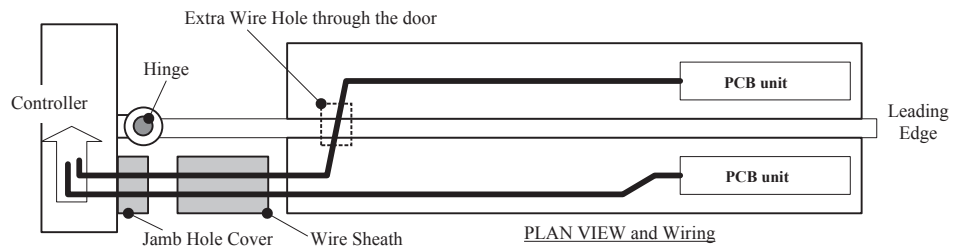
Connect the wires to the door controller using the Terminal Block

Wire size 0.15 to 3.5 [mm²]

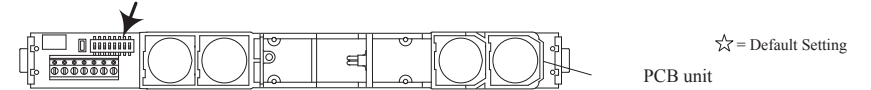


1	Power supply (AC/DC 12~24[V])
2	Relay Output (Common)
3	Relay Output (Normal Open)
4	Relay Output (Normal Close)
5	TEST Input (-)
6	TEST Input (+)
7	

3.6 Plan View of Installation (both sides of the door)



4 Dip Switch Settings



4.1 TEST Input

When connected to a door controller without a TEST input, set to "A". When connected to a door controller with a TEST input, set to "B". Refer to [6. Timing Chart of events].

EN16005 Set to "B" to comply with EN16005

4.2 Optical Interference

When two RAP5M-PRO are installed in close proximity, optical cross interference between them might cause mis-operation. To avoid this, different frequency settings should be selected using DIP Switch #2.

4.3 Relay Output Mode

Refer to [6. Timing chart of events] for full details on Relay Output Mode.

☆ NO 3 NC 3

4.4 Masking detecting spots

4.5 Detection Range

Set Non-Detection distance (A)

EN16005 Check that the detection range conforms to EN16005

50mm	250mm
100mm	300mm
150mm	400mm
200mm	500mm

5 Detection Angle Adjustment

The detection angle can be adjusted between 5 ~ 25 [deg] in 5 [deg] increments using the Angle Stabilizer.

Example) Changing angle from 5° to 25°

- Slide
- Lift
- Rotate PCB unit
- Slide Back

PCB unit

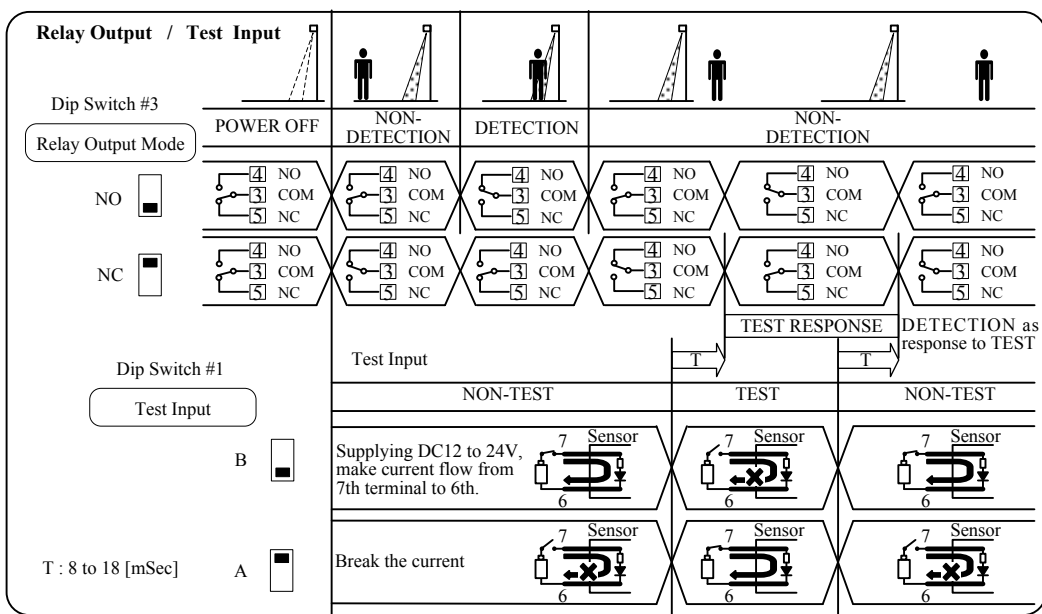
Angle Stabilizer

25°

5°

EN16005 Check that the detection area position conforms to EN16005

6 Timing chart of events

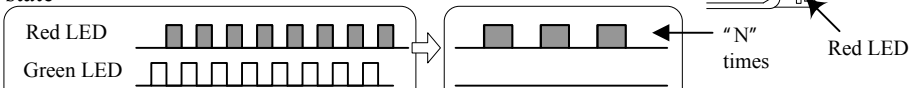


7 LED information

7-1 Normal state

State	Red LED	Green LED
Non-Detect	○ OFF	● ON
Detect	● ON	○ OFF

7-2 Error state



N	Error category	Cause	Solution
1	Environmental error	Environmental noise or the reflection level from the floor is too low.	Execute the "TEACH" from Section 8 whilst laying a sheet of white paper on the floor.
3 over	Other Error	Internal component failure	Change the units.

7-3 Teaching state See Section 8

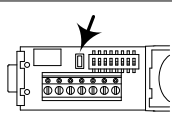
8 Teaching

Conduct the following steps with the Filter Cover off.

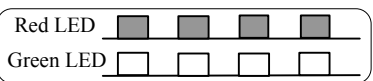
- Check the wiring connection and supply power.
- Execute "TEACHING"

"TEACHING" is necessary to make the sensor work properly, that is to learn the distance from the sensor to the floor.

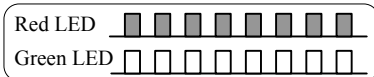
STEP 1.
Press the "Push SW" switch for more than 2 seconds.



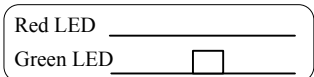
STEP 2.
LED blinks slowly for 10 sec's in a non-detection state. Ensure that there are no people or objects (ladder etc) in the detection area during this time.



STEP 3.
After STEP2, LED blinks faster and starts "TEACHING". If during this time, a person or object is in the detection area, try again from STEP 1.



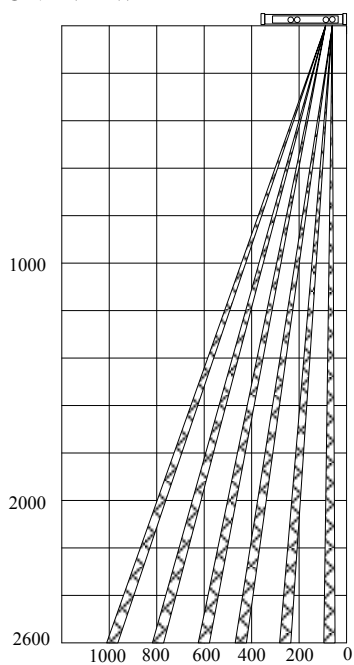
STEP 4.
After STEP3, the green LED blinks once and then this process is completed.



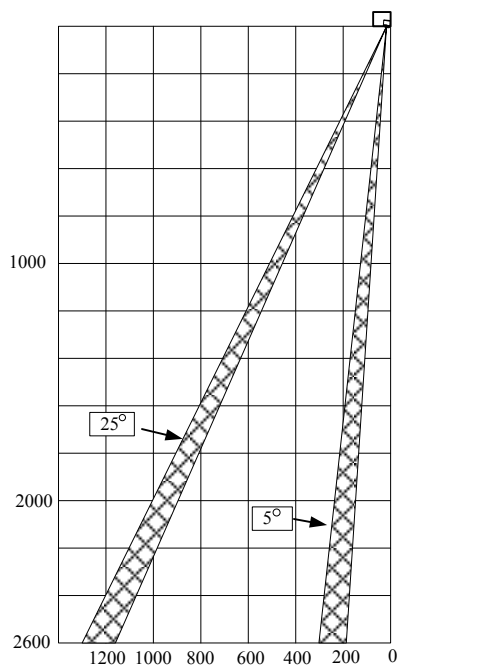
- Check the adjustments, range and other setting.

9 Detection Area

9.1 FRONT VIEW



9.2 SIDE VIEW



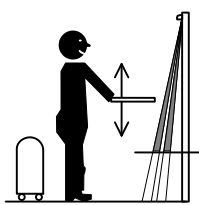
10 Detection Range Check without Filter Cover

Check the detection range without the Filter Cover attached. Put a test object in the detection area to check the detection patterns and other Dip Switch settings. Tests according to local standards should be carried out.

After this check, Turn power off.

EN16005 Check that the detection area conforms to EN16005

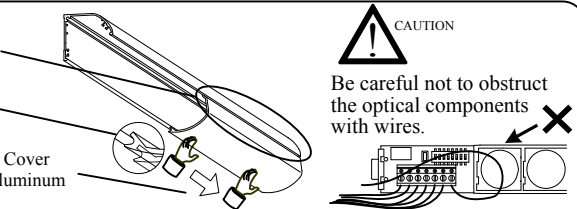
When the test is completed, go to Section 11 to install the Filter Cover and Side Cover. If an error occurs, re-check the settings referring to Section 3.



11 Replacing the Filter Cover and Side Cover

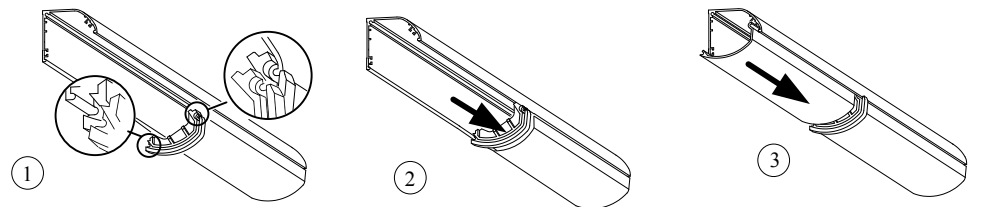
1 Installing the Filter Cover:

- First fit the upper side of the Filter Cover into the full length of the Aluminum Case.
- Slightly bend the Filter Cover at one end to latch it onto the bottom lip of the Aluminum Case.
- Slide your hand along the bottom lip to lock the Filter Cover onto the Aluminum Case all along the length of the Aluminum Case.

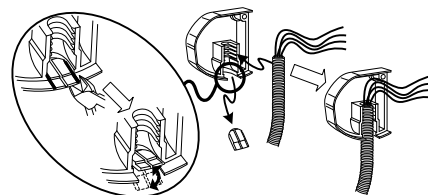


2 Attaching the Joint

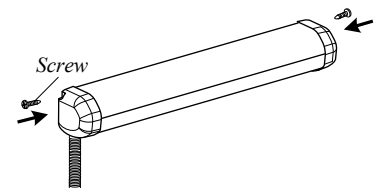
- Snap the Joint into the Aluminum Case.
- Slide the Joint so that it fits snugly into the Filter Cover. Make sure there are no gaps left.
- Attach remaining Filter Covers as illustrated



3 Cut out the Side Cover wiring point and insert the Wire Sheath into it.



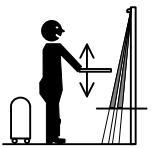
4 Attach the Side Cover with Screws provided.



12 Final Detection Range Check

After the Filter Cover is fitted, confirm that the detection range is as expected and conforms with local regulations.

EN16005 Check that the detection area conforms to EN16005

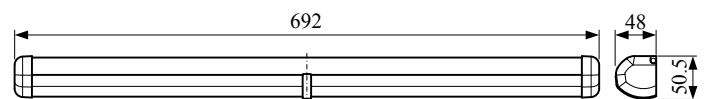


13 Technical Data

MODEL	Safety Sensor for Swing Doors		
TECHNOLOGY	COMPLETE STATIONARY DETECTION with PSD DISTANCE MEASUREMENT		
POWER SUPPLY	AC/DC 12~24[V] ± 10%	BEAM ANGLE ADJUSTMENT	5, 10, 15, 20, 25 [degrees]
CURRENT CONSUMPTION	95 [mA] @ DC12[V] 55 [mA] @ DC24[V] 1.7 [VA] @ AC12 [V] 2.3 [VA] @ AC24[V]	RESPONSE SPEED	LESS THAN 100 [mSec]
	RELAY OUTPUT	DC 50V 0.1 [A] NON VOLTAGE 1C	DIP SW FUNCTIONS
TEST INPUT	6 [mA] Max. at 24 [VDC]	OPERATING TEMPERATURE	-20 ~ +60 [°C]
MOUNTING HEIGHT	2.6 [m] Max	WEIGHT	540[g] APPROX.
DETECTION RANGE	0 - 2.55 [m] Max		

14 Dimensions

Unit: [mm]



<Disclaimer> The manufacturer cannot be held responsible for the below.

- Misinterpretation of the installation instructions, miss connection, negligence, sensor modification and inappropriate installation.
- Damage caused by inappropriate transportation.
- Accidents or damages caused by fire, pollution, abnormal voltage, earthquake, thunderstorm, wind, floods and other acts of providence.
- Losses of business profits, business interruptions, business information losses and other financial losses caused by using the sensor or malfunction of the sensor.
- Amount of compensation beyond selling price in all cases.

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